

# Pyroelectric Infrared Radial Sensor

TYPE: AM312
NANYANG SENBA OPTICAL AND ELECTRONIC CO., LTD.



# **Digital Intelligent Passive Infrared Sensor AM312**

AM312 is a new digital intelligent PIR sensor. This Smart digital detector offers a complete motion detector solution, with all electronic circuitry built into the detector housing. Only a power supply and power-switching components need to be added to make the entire motion switch.

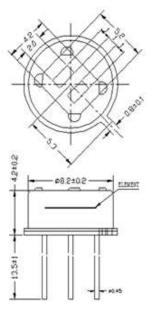
## **■** Features and Benefits

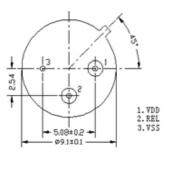
- Digital signal processing (DSP)
- Two-way differential high impedance sensor input and temperature compensation
- Built-in filter, screen the interference by other frequency
- Schmidt REL output

## **■** Applications

USB Alarms, PIR motion detection, Intruder detection, Occupancy detection, Motion sensor lights, Network camera, Car-security system etc.

## ■ Dimension







# ■ Technical Data

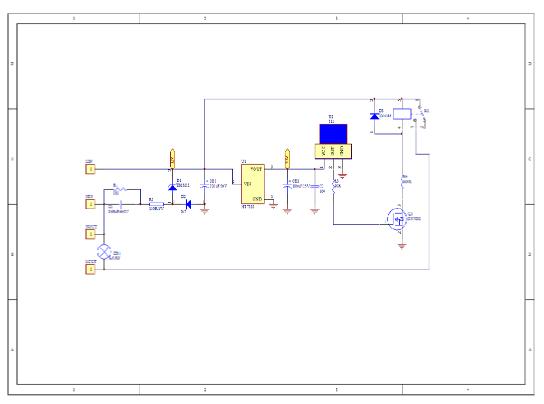
# 1. Maximum Ratings

| Characteristics      | Symbol | Min.<br>Value   | Max.<br>Value | Unit       | Remarks |
|----------------------|--------|-----------------|---------------|------------|---------|
| Supply Voltage       | VDD    | -0.3            | 3.6           | <b>V</b>   |         |
| Working Temperature  | TST    | <b>-</b> 20     | 85            | $^{\circ}$ |         |
| Current into any pin | Into   | <b>-</b> 100    | 100           | mA         |         |
| Storage Temperature  | TST    | <del>-</del> 40 | 125           | $^{\circ}$ |         |

| 2.Working Conditions (T=25℃, Vdd=3V, Except other requirements) |       |      |      |      |                     |      |  |  |  |
|---|-------|------|------|------|---------------------|------|--|--|--|
| Characteristics   | Sy    | mbol | Min. | Туре | Max.                | Unit | Remarks  |  |  |
| Supply Voltage  | \     | /DD  | 2.7  | 3    | 3.3                 | V    |  |  |  |
| Working Current   | IDD   |      | 12   | 15   | 20                  | μA   |  |  |  |
| Sensitivity Threshold<br>Value                                  | Vsens |      |      | 120  |                     | μV   | Non-adjustable                                       |  |  |
| Output REL  |       |      |      |      | 1                   | •    |  |  |  |
| Output Low Current  |       | IOL  | 10   |      |                     | mA   | VOL<1V   |  |  |
| Output High Current   |       | IOH  |      |      | -10                 | mA   | VOH>(VDD-1V)   |  |  |
| REL Low Level Output Blockade Time                              |       | TOL  |      | 2.3  |                     | s    | Non-adjustable                                       |  |  |
| REL High Level Output<br>Delay Time                             |       |      |      | 2.3  |                     | s    |  |  |  |
| Oscillator & Filter   | r     |      |      |      |                     |      |  |  |  |
| Low pass filter cut-off frequency                               |       |      |      |      | 7                   | Hz   |  |  |  |
| High pass filter cut-off frequency                              |       |      |      |      | 0.44                | Hz   |  |  |  |
| Oscillator frequency on   | Chip  | FCLK |      |      | 64                  | kHz  |  |  |  |
| Interior Block Diaç   | gram  |      |      | 140  | OCC<br>TIME GAP SEF |      | Oup4 CEL.  e Evort Logic  St control Logic  VDD  VSS |  |  |

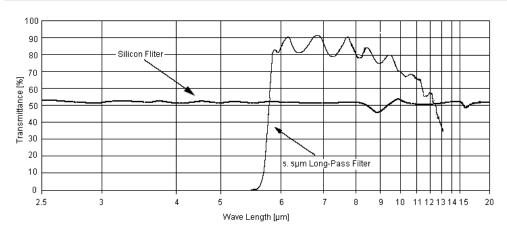


# **■** Typical Application



Notes: This is only reference circuit for PIR Sensor AM312.

# ■ Spectral Response of Window Materials



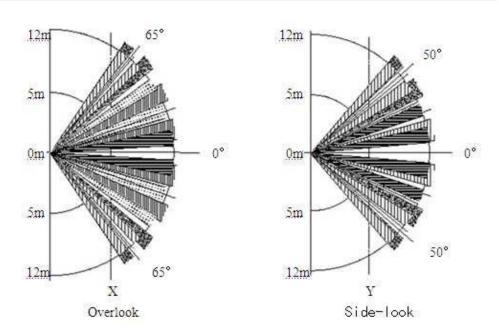
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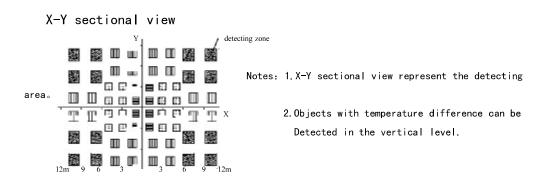


Notice:

The typical average transmissivity curve of 5.5µm pass IR filter is figured, which is vacuumed on silicon filter.

# **■ View of Field**





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## Directions for Use

- •Pay attention to the mounting direction of the sensor's element and the size of element ichnography. Combining with focus of Fresnel lens can achieve a optimal optics design.
- •The ex-factory parameter of sensor is gained by testing in the condition of standard Black Body and the relevant circuit after one minute steadying-time.
- •The detecting distance of sensor is a multidimensional function, consisting of ambient temperature, temperature of moving target, target distance of Fresnel Lens', ambient humidity, amplifier gain and comparison voltage.
- •The welding shall be made at 4mm above as per the recommendation for lead wire of sensor seat, and the welding should be completed in the shortest possible time.
- •Do not touch the window by hand and the hard things directly.
- Strong shake and static should be avoided.
- •This products are packed with the environmental protection material ,and the sensors' surface has been covered specially with OHK anti-erode material,100pcs per small package ,3000pcs per large package.



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